

Math 8500 Algorithmic Graph Theory, Spring 2017, OSU
 Lecture 4: Max-Cut and Szemerédi's Regularity Lemma (cont.)
 Instructor: Anastasios Sidiropoulos
 Scribe: Jason Bello

1 ℓ -Way Cut / Max ℓ -Cut Problem

Input: $G=(V,E)$ (assume unweighted for simplicity), $n = |V|$.

Goal: Find partition $S = S_1, \dots, S_\ell$ of V maximizing $|E(S)|$ where
 $E(S) = \{\{u, v\} : u \in S_i, v \in S_j \text{ for some } i \neq j\}$.

This is another problem for which we do not know an algorithm that outputs an optimal solution, but as we will show, our algorithm can output a solution that is “close” to optimal. Before we can express our algorithm, we need to set up some notation and state an important lemma.

So let $G = (V, E)$ and $A, B \subseteq V$, then let $e(A, B) = |E(A, B)|$ where $E(A, B)$ is the set of edges between A and B . Now let $d(A, B) = \frac{e(A, B)}{|A| \cdot |B|}$. Now we can state the following definition.

Definition 1. Suppose $A \cap B = \emptyset$. Then we say that (A, B) is ε -regular if for all $X \subseteq A$ with $|X| \geq \varepsilon|A|$ and for all $Y \subseteq B$ with $|Y| \geq \varepsilon|B|$, we have $|d(X, Y) - d(A, B)| < \varepsilon$.

With this notation and definition at our disposal we can now state Szemerédi's Regularity Lemma.

Lemma 1 (Szemerédi's Regularity Lemma). *For all $\varepsilon > 0$, for all $m \in \mathbb{Z}^+$, there exists $P(\varepsilon, m), Q(\varepsilon, m) \in \mathbb{Z}$ such that for all graphs $G = (V, E)$ with $n \geq P(\varepsilon, m)$ there exists partition V_1, \dots, V_k of V such that*

- i. $m \leq k \leq Q(\varepsilon, m)$;*
- ii. $\lceil \frac{n}{k} \rceil - 1 \leq |V_i| \leq \lceil \frac{n}{k} \rceil$;*
- iii. All but εk^2 of the pairs (V_i, V_j) are ε -regular.*

Remark. Partitions that satisfy *iii.* in Szemerédi's Regularity Lemma are called ε -regular partitions.

Now let us develop some more notation. Let V_1, \dots, V_k is a partition of V , $K = \{1, \dots, k\}$, and $d_{i,j} = d(V_i, V_j)$. For $X \subseteq V$, $I \subseteq K$, let $X_I = \cup_{i \in I} X_i$ where $X_i = X \cap V_i$. Let $S, T \subseteq V$ such that $S \cap T = \emptyset$. Let

$$\Delta(S, T) = e(S, T) - \sum_{i \in K} \sum_{j \in K} d_{i,j} \cdot |S_i| \cdot |T_j|.$$

Remark. If (V_i, V_j) is ε -regular then $e(S_i, T_j) \approx d_{i,j} \cdot |S_i| \cdot |T_j|$. In other words, $\Delta(S, T)$ measures the “deviation from regularity”.

Definition 2. We say that V_1, \dots, V_k is ε -sufficient if $|\Delta(S, T)| \leq \varepsilon n^2$ for all $S, T \subseteq V$ with $S \cap T = \emptyset$.

The following lemma will tell us that as long as k is large enough the partition given by Szemerédi’s Regularity Lemma is also 4ε -sufficient.

Lemma 2. *An ε -regular partition with $k \geq \frac{1}{\varepsilon}$ is 4ε -sufficient.*

Proof. Suppose V_1, \dots, V_k is ε -regular partition and $v = \lceil \frac{n}{k} \rceil$ where n, k are as defined in Szemerédi’s Regularity Lemma. Let $S, T \subseteq V$ such that $S \cap T = \emptyset$ and let

$$\begin{aligned} L_2 &= \{(i, j) \in K \times K : |S_i| \leq \varepsilon v \text{ or } |T_j| \leq \varepsilon v\}, \\ L &= \{(i, j) \in K \times K : i \neq j \text{ and } (V_i, V_j) \text{ is } \varepsilon\text{-regular}\}, \\ L_1 &= L \setminus L_2, L_3 = (K \times K) \setminus (L_1 \cup L_2), \text{ and } L_4 = \{(i, i) : i \in K\} \end{aligned}$$

Then $\Delta(S, T) = \Delta_1 + \Delta_2 + \Delta_3 + \Delta_4$ where $\Delta_i = \sum_{(i,j) \in L_i} (e(S_i, T_j) - \sum_{j \in K} d_{i,j} \cdot |S_i| \cdot |T_j|)$. So then we have that for all $i \in \{1, 2, 3, 4\}$, $\Delta_i \leq \varepsilon r^2 k^2$ and so $\Delta(S, T) \leq 4\varepsilon n^2$. Thus, the partition is 4ε -regular. \square

An important side-note that we’ve been omitting is if these ε -regular partitions can be computed in a reasonable amount of time. Szemerédi’s Regularity Lemma tells us that they exist but not necessarily that we can construct them efficiently. Luckily, our next theorem does.

Theorem 1 (Alon, Duke, Lehmann, Rodd, Yuster). *An ε -regular partition can be efficiently computed.*

The following theorem solves the problem with a close to optimal partition.

Theorem 2. *There is a randomized polynomial time algorithm which given an n -vertex graph G , with probability at least $3/4$, computes a partition S_ε such that $|E(S_\varepsilon)| \geq |E(S^*)| - \varepsilon n^2$ where S^* is an optimal partition.*